

Fast, Accurate Simulation for SDN Prototyping

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Overview

- Motivation
- Related Work
- Goals
- *fs-sdn* overview and background
- Design and Implementation
- System Evaluation
- Results: Speedup and Accuracy
- Summary

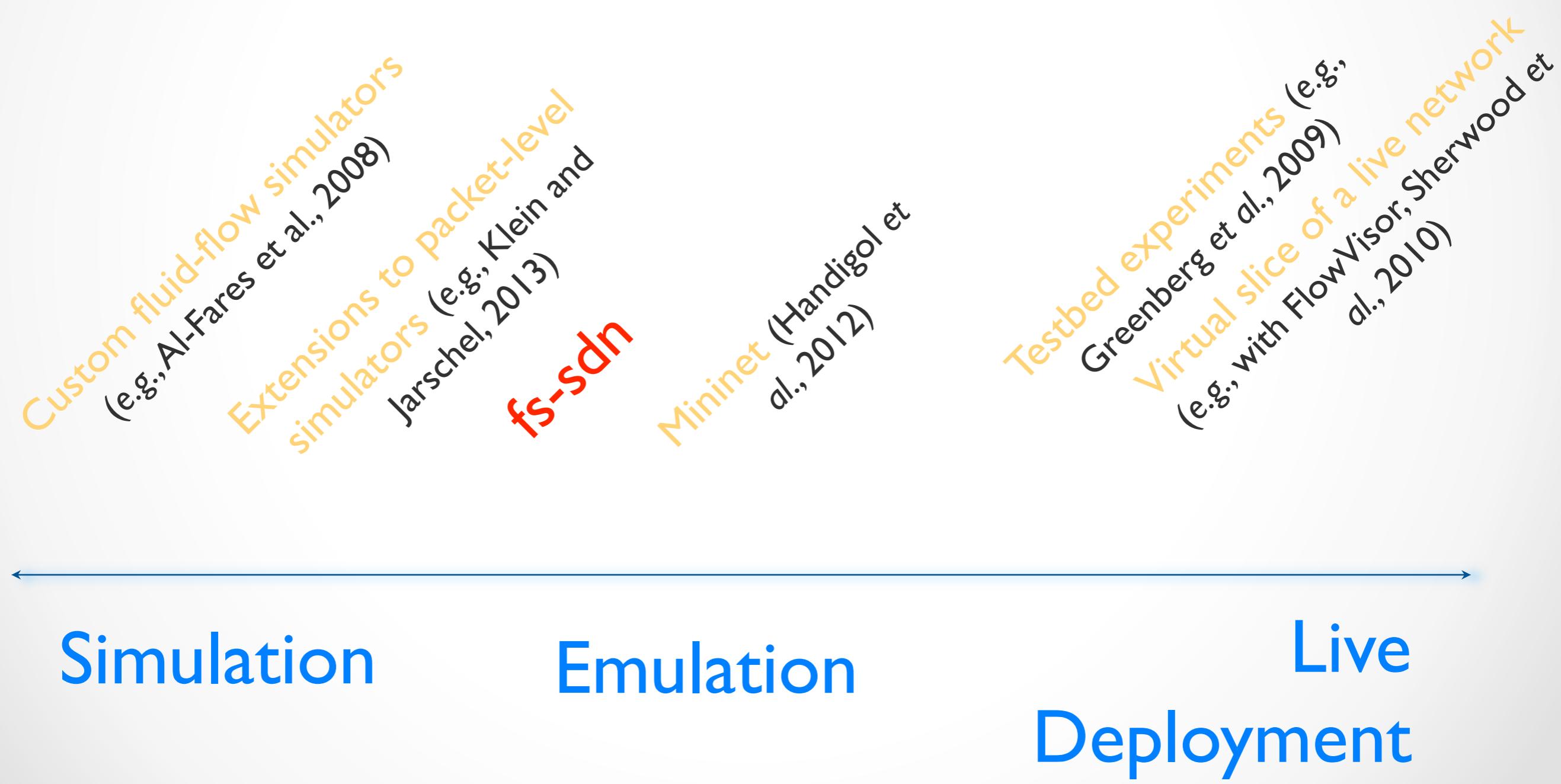
Motivation

- Prototyping, evaluating and debugging SDN applications is hard
 - Increasing **scale, diversity, and complexity** of apps
 - Will my SDN app **behave** as **expected** when deployed in the wild?
 - Does it **operate** correctly and efficiently **at scale**?

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SDN prototyping and debugging landscape



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Goals

- A controller **API environment** to facilitate transition to live environments
- Ability to generate **realistic** application traffic flows
- Capability to **scale up** to large networks
- Facilities for detailed **debugging** and **tracing**

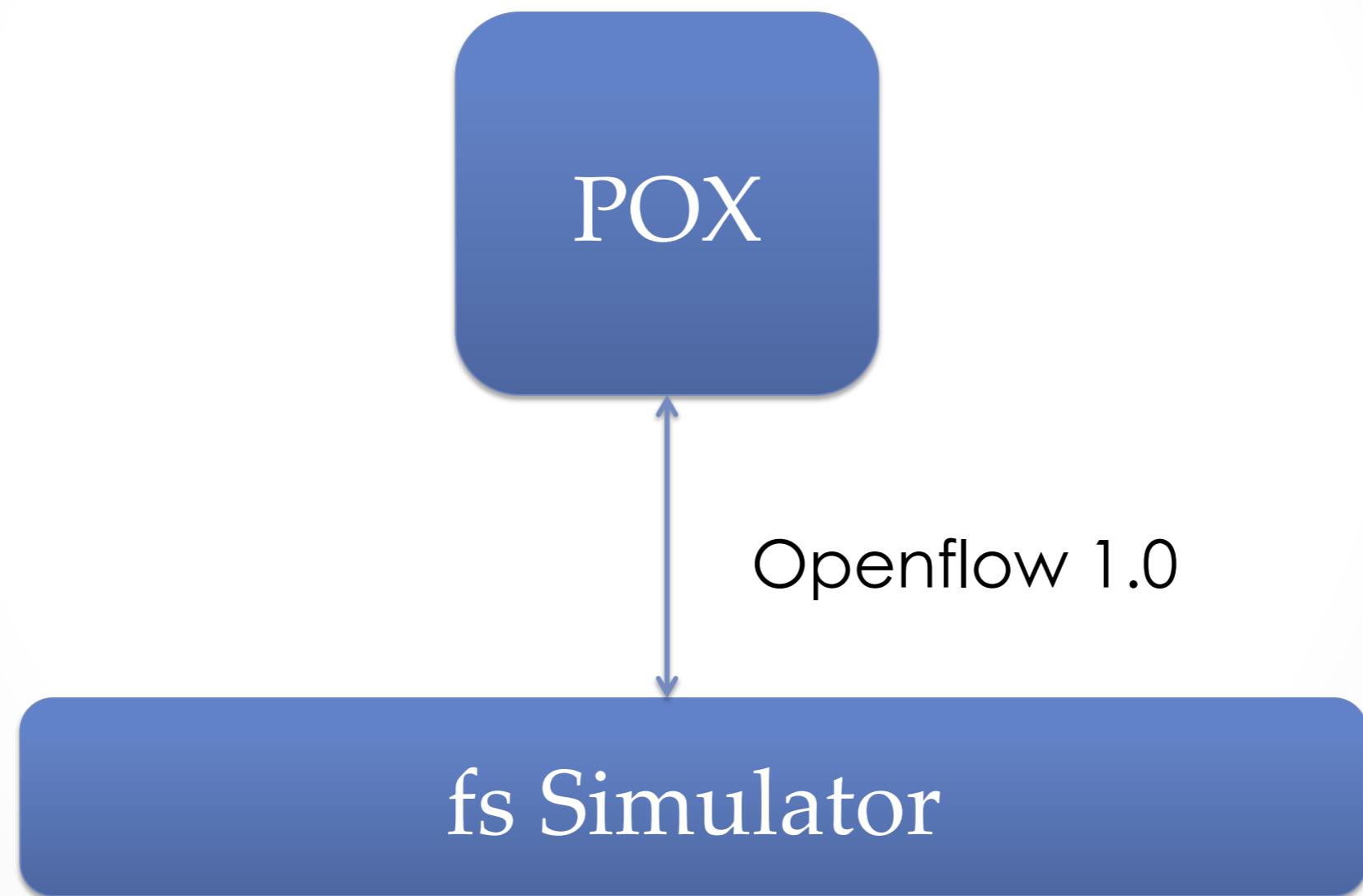
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fs-sdn Background

- Designed as extensions to the *fs* network flow record generator (INFOCOM 2011)
 - Written in Python
 - Uses discrete event simulation to drive flow record generation
 - Flowlets instead of packets
 - Accurate to 1 second time scales, way faster than ns2

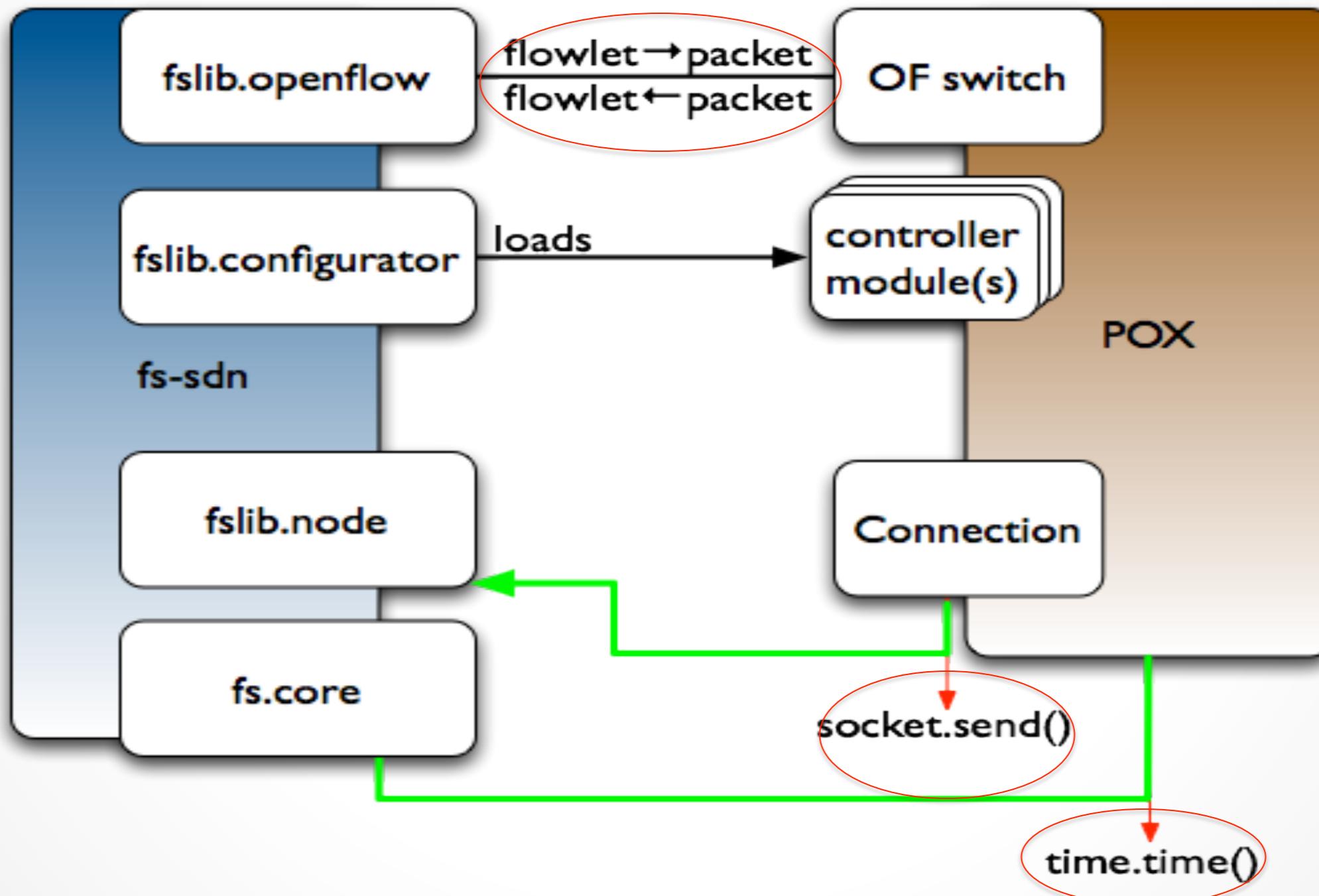
fs-sdn Design



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fs-SDN design and implementation



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System evaluation

- Set up congruent experiments in fs-sdn and Mininet

Traffic

- CBR
(10 and 100 Mbps)
- Harpoon Traffic
(5 and 25 Mbps)

Topology

- 1
- 10
- 50
- 100

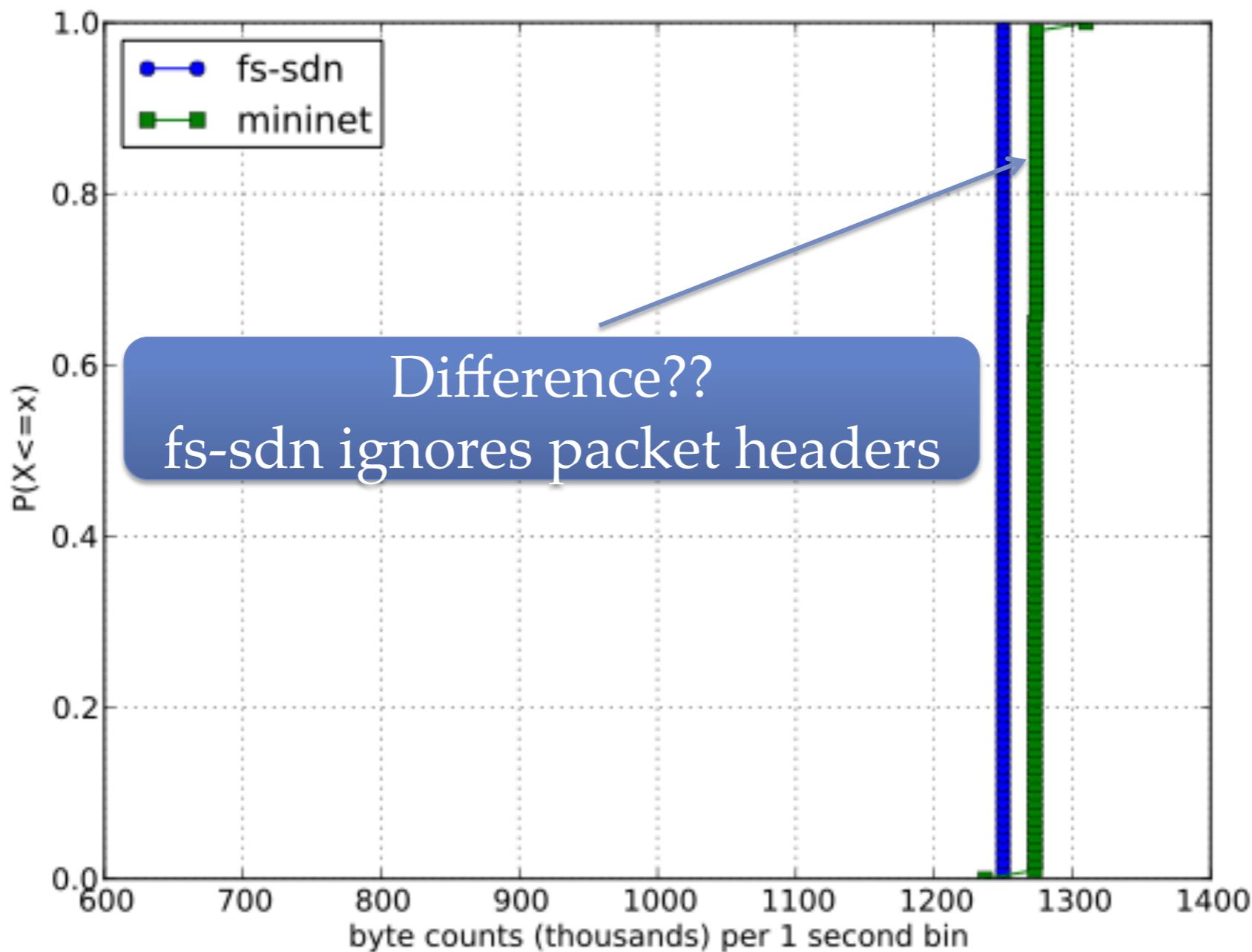
Controller

- L3 Shortest Path

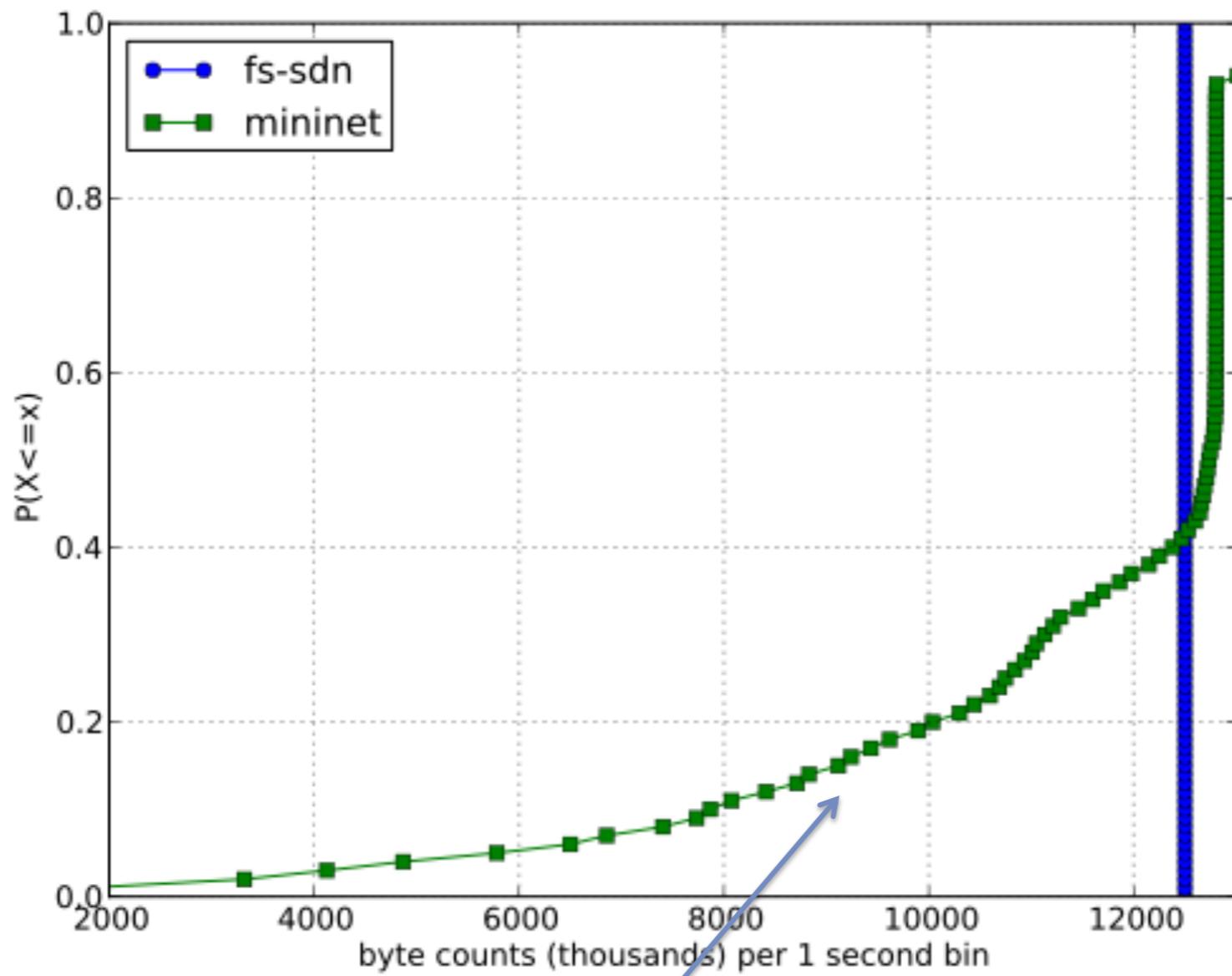
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Results: accuracy

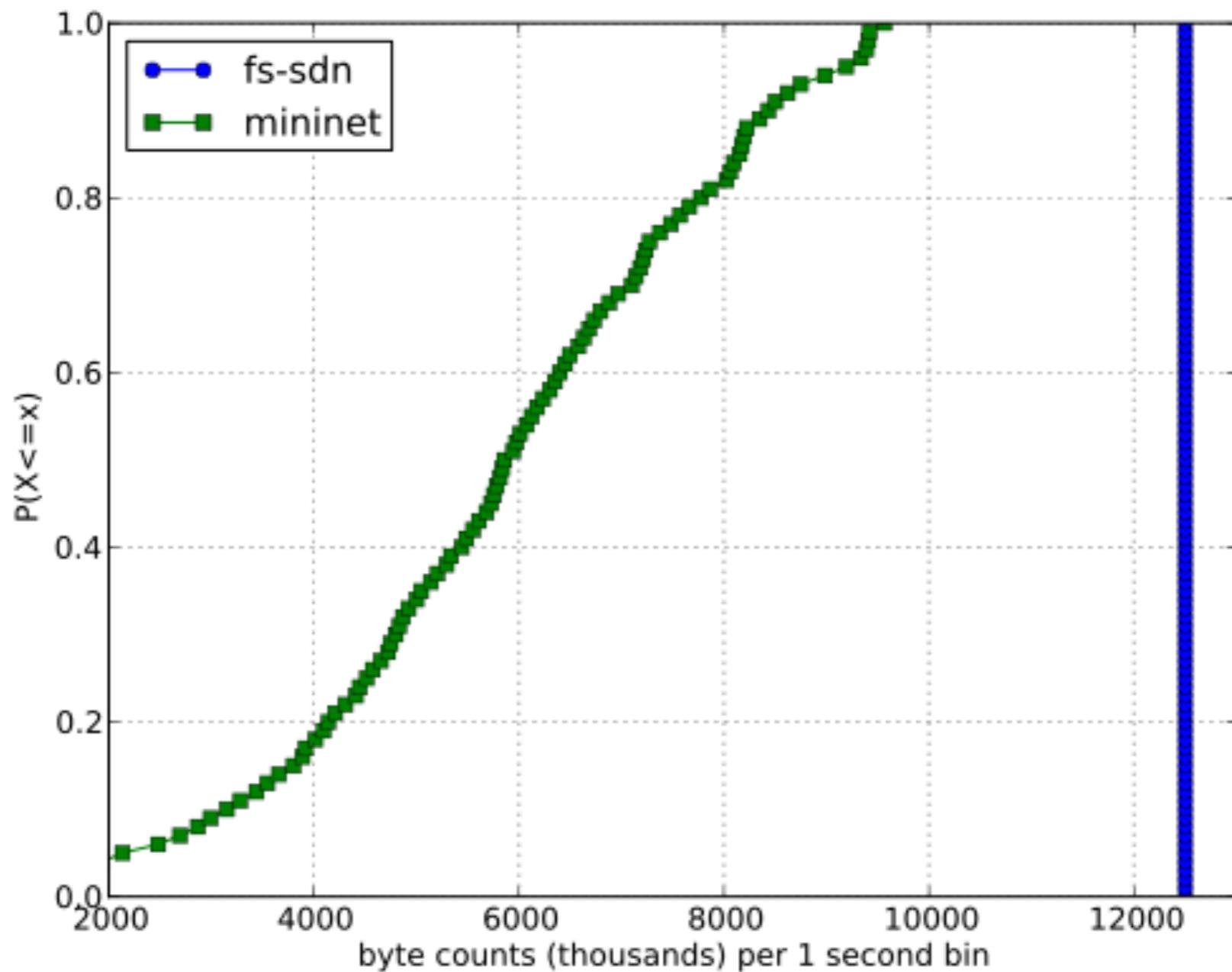


Results: accuracy



Performance impact of underlying host

Results: accuracy



CBR high load (100 Mb/s),
medium topology (50 switches)

Results: speedup

- Tables show fs-sdn execution times for scenarios with **900 simulated seconds**

UDP CBR traffic				
Load	Tiny	Small	Medium	Large
Low	6	8	33	72
High	4	8	31	76

Harpoon traffic (Pareto distr. flow sizes)				
Load	Tiny	Small	Medium	Large
Low	16	33	104	193
High	30	62	194	337

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Summary and future work

- Fast and Accurate Simulation
- Seamless transition of controllers to “real” deployments
- Code available: <https://github.com/jsommers/fs>
- Continued work
 - Debugging and tracing capability
 - Improve scalability through parallelizing fs
 - Is it possible to bridge other (including non-Python) controller platforms?

Thank You

Questions?



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